

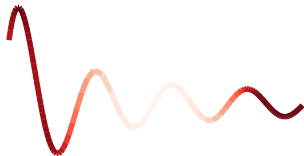
Generalized Energy Based Models

Michael Arbel¹ Liang Zhou¹
Arthur Gretton¹

¹Gatsby Computational Neuroscience Unit
University College London

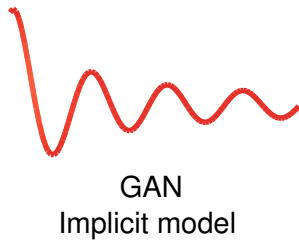
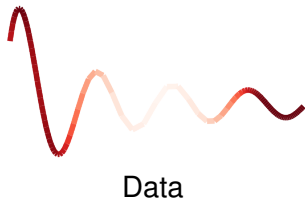
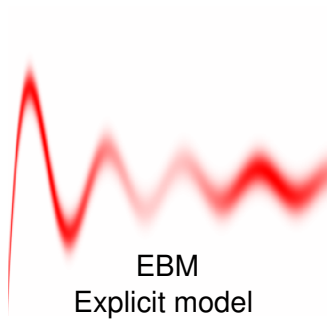
February 22, 2021

Data with low intrinsic dimension: A toy example

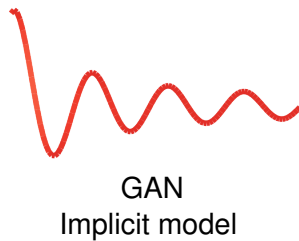
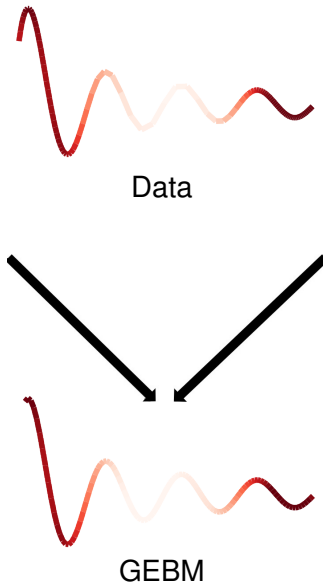
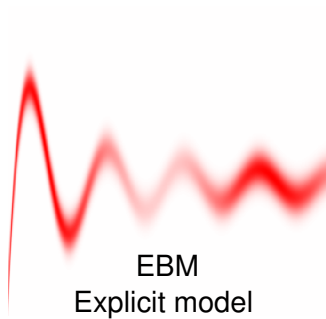


Data

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Outline

- ▶ Data with low intrinsic dimension: The need for new models

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- ▶ Conclusion and future work

Data with low intrinsic dimension: Natural Images¹

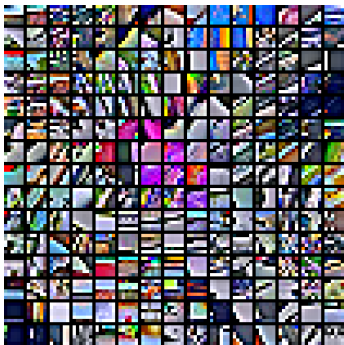
Topographical Ordering of
ImageNet patches



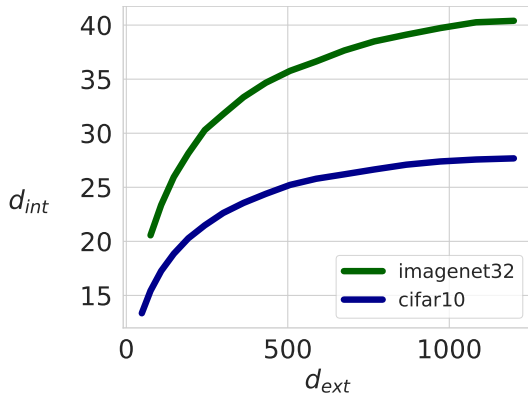
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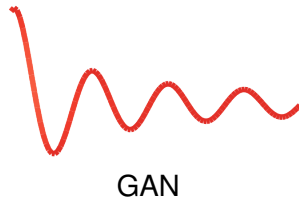
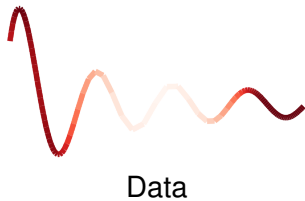
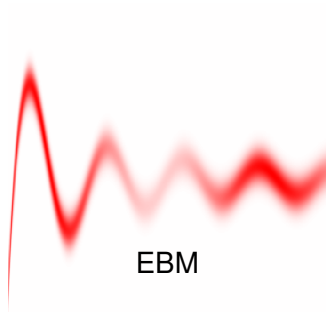


Nearest Neighbor dimension

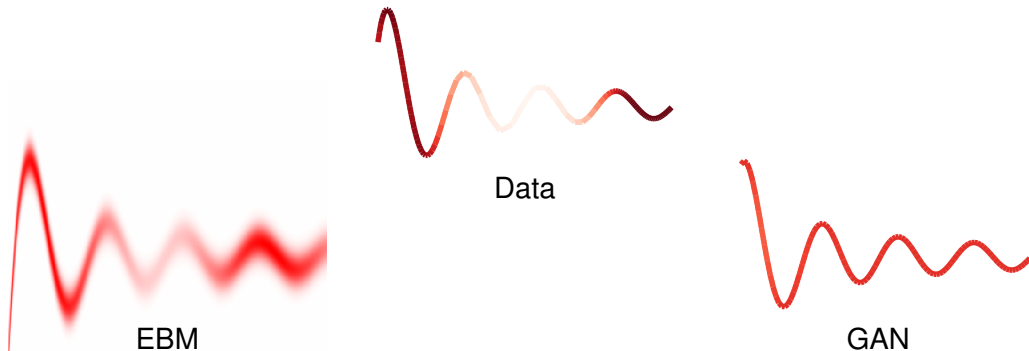


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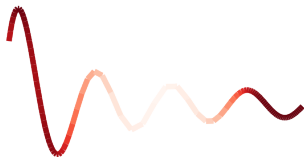
EBM

Data

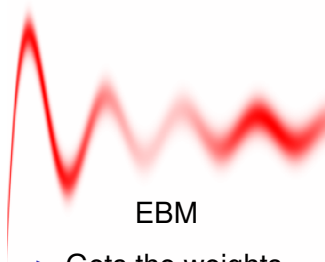
GAN

- ▶ Gets the weights...
- ▶ But blurs the samples
- ▶ Needs powerful energy models

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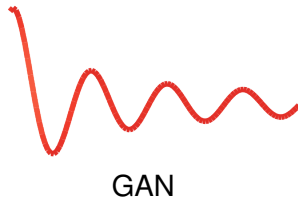


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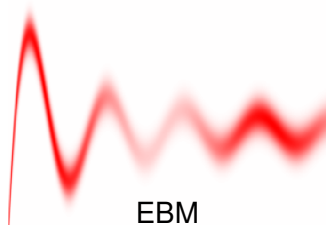
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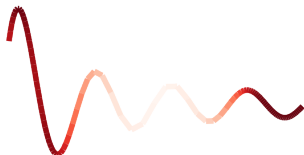
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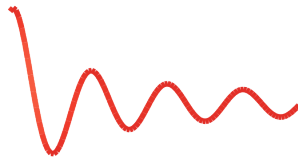
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Data

Can we do better?



GAN

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Generalized Energy-Based Models

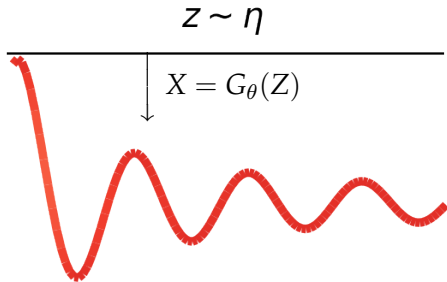
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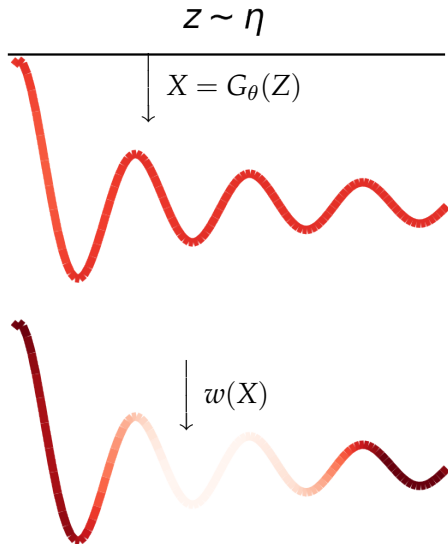
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- ▶ Samples are re-weighted according to importance weights defined by the energy:

$$w(X) \propto \exp(-E(X))$$

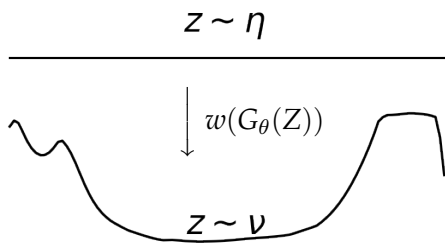


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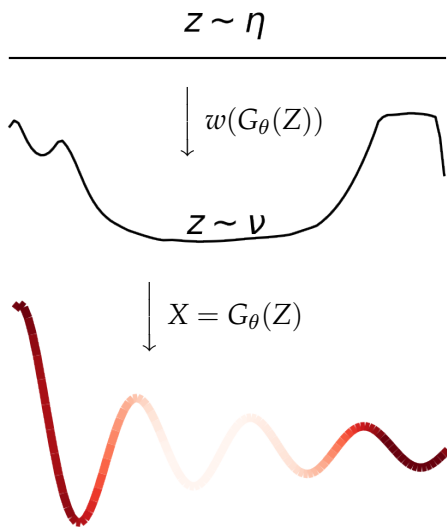


- ▶ Latents are sampled according to a 'posterior' distribution:

$$\nu(Z) = \eta(Z)w(G_\theta(Z))$$

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- ▶ Latents are sampled according to a 'posterior' distribution:

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- ▶ Latents are mapped to sample space using the implicit map G_θ :

$$X = G_\theta(Z)$$

Generalized Energy-Based Models: Why Generalized ?

- ▶ A GEBM can be written formally in terms of the *base* \mathbb{B}_θ and *energy* E :

$$d\mathbb{Q}(X) \propto \exp(-E(X)) d\mathbb{B}_\theta(X)$$

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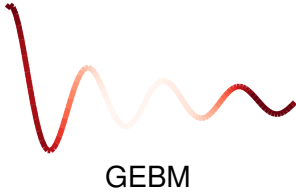
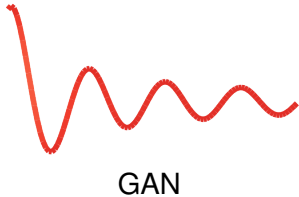
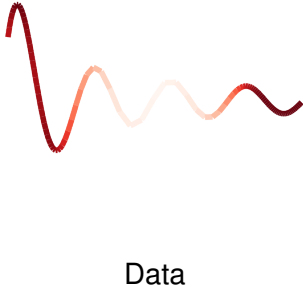
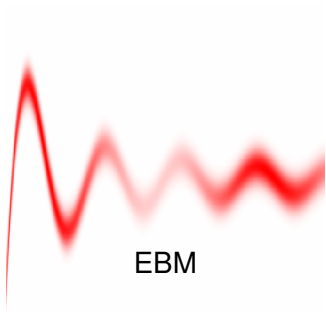
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- ▶ GEBM is a generalization of those models that takes the best of both worlds.

GEbMs: The best of both worlds

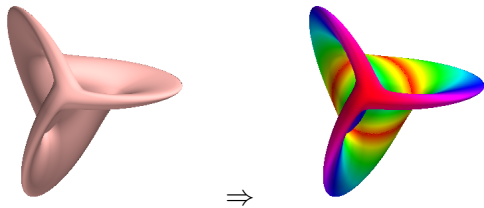


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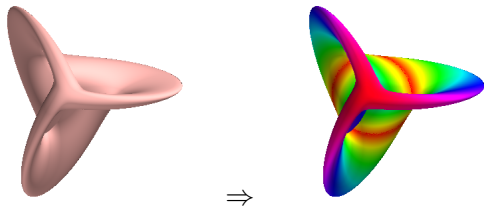
Training GEBM: A two steps approach

Training the energy: Generalized Maximum Likelihood

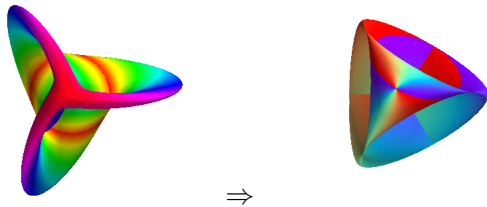


Training GEBM: A two steps approach

Training the energy: Generalized Maximum Likelihood



Training the base: f -divergence minimization (KALE)



Training the energy: Generalized Maximum Likelihood

Definition (Generalized Likelihood)

The expected \mathbb{B}_θ -log-likelihood under a target distribution \mathbb{P} of a GEBM model \mathbb{Q} with base \mathbb{B}_θ and energy E is defined as

$$\mathcal{L}_{\mathbb{P},\mathbb{B}}(E) := - \int E(x) d\mathbb{P}(x) - \log(Z_{\theta,E}).$$

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- ▶ Dependence on \mathbb{B}_θ through $Z_{\theta,E} = \mathbb{E}_{\mathbb{B}_\theta}[\exp(-E(X))]$.
- ▶ When $KL(\mathbb{P}, \mathbb{B}_\theta)$ is well defined: called **Donsker-Varadhan** lower bound on KL.
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 - ▶ Tight when $E(X) = -\log\left(\frac{d\mathbb{P}}{d\mathbb{B}}(X)\right)$
- ▶ However, *Generalized Log-Likelihood* is still well defined when \mathbb{P} and \mathbb{B}_θ are mutually singular

Training the energy: Generalized Maximum Likelihood

Learn the energy E using Generalized Log-Likelihood and keep the base \mathbb{B}_θ fixed.

$$\mathcal{L}_{\mathbb{P},\mathbb{B}}(E) := -\mathbb{E}_{\mathbb{P}}[E(X)] - \log(Z_{\theta,E}).$$

- ▶ Learn parameters of E using SGD.

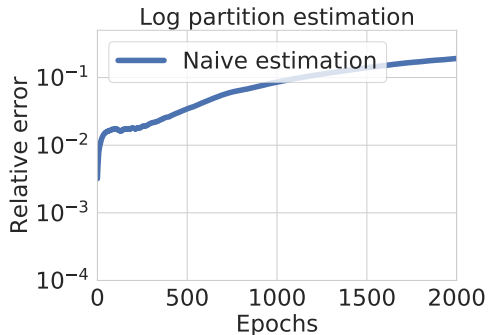
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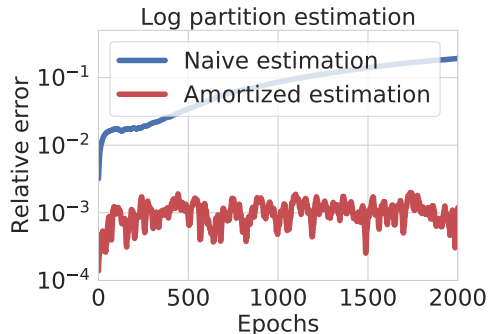
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- ▶ **Amortized estimation**: A better alternative.



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- ▶ Amortized estimation using a lower-bound on the log-likelihood:

$$\begin{aligned}\mathcal{L}_{\mathbb{P},\mathbb{B}}(E) &\geq -\mathbb{E}_{\mathbb{P}}[E(X) + c] - \mathbb{E}_{\mathbb{B}_\theta}[\exp(-(E(X) + c))] + 1 \\ &:= \mathcal{F}_{\mathbb{P},\mathbb{B}}(E + c)\end{aligned}$$

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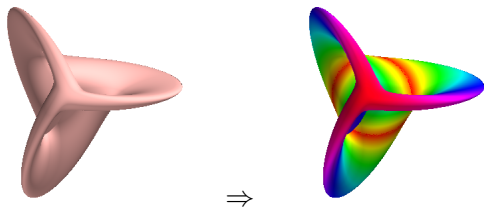
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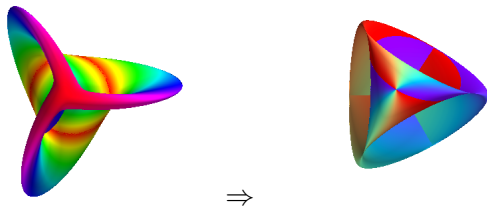
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- ▶ Parameter c keeps a memory of previous mini-batches.

Training GEBM: A two steps approach

Training the energy: Generalized Maximum Likelihood



Training the base: f -divergence minimization (KALE)



Training the base: KALE minimization

- ▶ Recall: Optimal energy E^* learned by keeping the base \mathbb{B}_θ fixed and maximizing:

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- ▶ KALE defines a divergence between distributions ... if the set of energies \mathcal{E} is rich enough: (ex: an MLP, an RKHS, etc).

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- ▶ Is the gradient well-defined? Is it smooth enough?

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- ▶ Lack of smoothness can result in instabilities during training²

²Chu, Minami, and Fukumizu, "Smoothness and Stability in GANs".

Training the base: Smoothness of KALE

- ▶ The loss results from an optimization:

$$KALE(\mathbb{P}, \mathbb{B}_\theta) = \sup_{E, c} \mathcal{F}_{\mathbb{P}, \mathbb{B}_\theta}(E + c)$$

- ▶ The gradient is expected to be of the form:

$$\nabla_\theta KALE(\mathbb{P}, \mathbb{B}_\theta) = \nabla_\theta \mathcal{F}_{\mathbb{P}, \mathbb{B}_\theta}(E^* + c^*)$$

- ▶ No guarantees this holds in general: needs additional assumptions.
- ▶ Typical assumptions rely on convexity³ of $\mathcal{F}_{\mathbb{P}, \mathbb{B}_\theta}(E + c)$ in the parameters of E , or measure smoothness assumptions⁴: too strong in this case.

³Sanjabi, Ba, Razaviyayn, and Lee, “Solving Approximate Wasserstein GANs to Stationarity”.

⁴Chu, Minami, and Fukumizu, “Smoothness and Stability in GANs”.

Training the base: Smoothness of KALE

Theorem (An envelope theorem)

$KALE(\mathbb{P}, \mathbb{B}_\theta)$ is Lipschitz and differentiable for almost all $\theta \in \Theta$ with:

$$\nabla_\theta KALE(\mathbb{P}, \mathbb{B}_\theta) = \mathbb{E}_{\nu_{\theta, E^*}} [\nabla_x E^*(G_\theta(Z)) \nabla_\theta G_\theta(Z)]$$

with ν_{θ, E^*} being the re-weighted latent distribution: $\nu_{\theta, E^*}(Z) \propto \exp(-E^*(G_\theta(Z)))$.

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Assumptions:

- ▶ Energies in \mathcal{E} parameterized by $\psi \in \Psi$, where Ψ is compact. Jointly continuous in (ψ, x) and L -smooth w.r.t. x .
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Proof idea:

- ▶ Characterization of differentiability for supremum-type functions⁵:
 - ▶ Expressions for left and right partial derivatives of the loss. Expressions match when $\theta \mapsto E_\theta^*$ is continuous.
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- ▶ Prove differentiability using Radamacher theorem.

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Training GEBM: Summary

GEBMs are defined by:

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Can we guarantee that the GEBM \mathbb{Q} is getting closer to \mathbb{P} ?

Theorem

If the set of energies \mathcal{E} is convex, then:

$$KALE(\mathbb{P}, \mathbb{Q}_{\theta,E^*}) \leq 2KALE(\mathbb{P}, \mathbb{B}_{\theta})$$

where E^ maximizes the generalized \mathbb{B}_{θ} log-likelihood*

Training GEBM: Does it really learn Maximum likelihood ?

Particular instance for GEBM:

- ▶ The base $\mathbb{B}_\theta(X)$ is a Real NVP⁶ (closed form density $\exp(h_\theta(X))$)
- ▶ The Energy is of the form $E(X) = r_\psi(X) - h_\theta(X)$
- ▶ For this choice, GEBM is equivalent to an EBM of the form

$$d\mathbb{Q}_{\theta,E}(X) \propto \exp(-r_\psi(X)) dX.$$

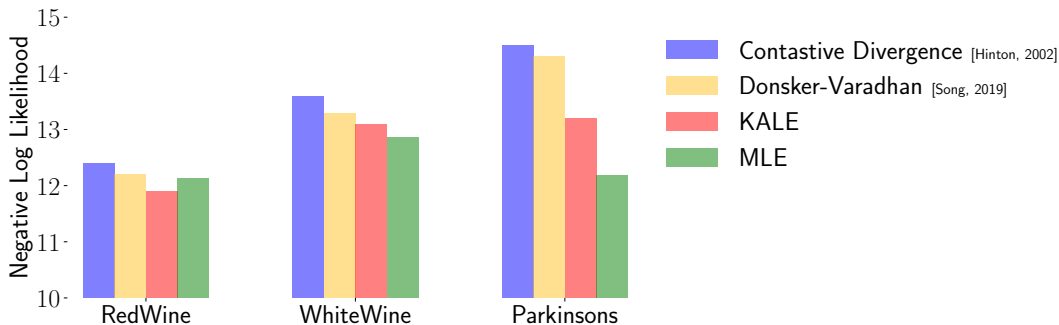
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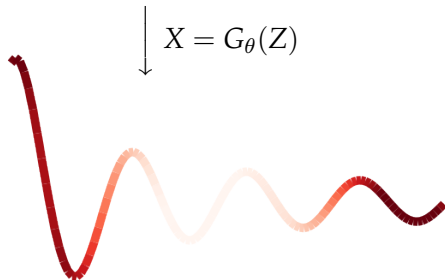
Sampling from GEBMs: Latent space MCMC

GEBMs are defined by $d\mathbb{Q}_{\theta,E}(X) = w(X) d\mathbb{B}_{\theta}(X)$ with $w(X) \propto \exp(-E(X))$.



- ▶ Latents are sampled according to a 'posterior' distribution:

$$\nu(Z) = \eta(Z)w(G_{\theta}(Z))$$



- ▶ Latents are mapped to sample space using the implicit map G_{θ} :

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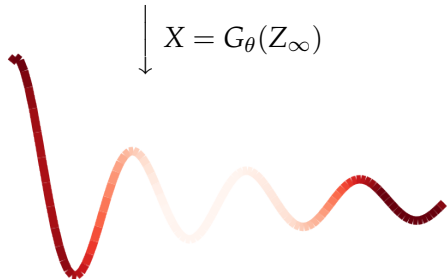
- ▶ In practice, use MCMC

$$W_{k+1} \sim \mathcal{N}(0, I)$$

$$Z_{k+1} = Z_k + \gamma \nabla_z \log \nu(Z_k) + \sqrt{2\gamma} W_{k+1}$$

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Outline

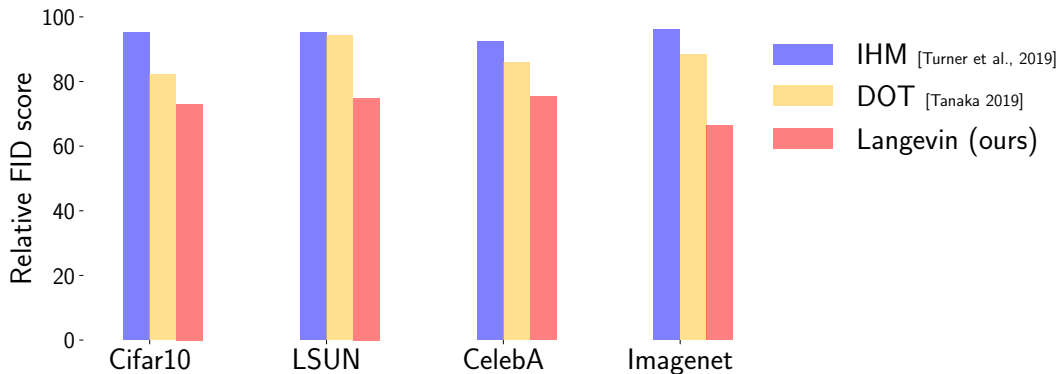
- ▶ Data with low intrinsic dimension: The need for new models
- ▶ Generalized Energy-Based models: A model with two components
 - ▶ The base
 - ▶ The energy
- ▶ Training GEBMs: a two stages method
 - ▶ Learning the energy: Generalized Maximum Likelihood Estimation
 - ▶ Learning the base : *KALE* minimization
- ▶ **Sampling from GEBMs**
 - ▶ Latent space MCMC
 - ▶ Experimental validation on image datasets.
- ▶ Conclusion and future work

Sampling from GEBMs: Latent space MCMC



Sampling for Generalized EBM

► Relative FID score: $\frac{FID(\mathbb{Q}_{\theta, E})}{FID(\mathbb{B}_{\theta})}$.



For a given base \mathbb{B}_{θ} and energy E trained using KALE, samples from the GEBM are always better (FID score) than samples from the base alone.

Sampling from GEBMs: Jumping between modes

Other samplers (ex. Hamiltonian Monte Carlo) allows better mode exploration



Summary

- ▶ GEBMs are models tailored for data with low intrinsic dimension
- ▶ Combine the strength of both **Implicit** (the base) and **Explicit** models (the energy)
- ▶ Two stages training : alternating optimization on the base and energy
- ▶ Sampling performed by Latent space MCMC
- ▶ Improves over sampling from the base alone (as done in GANs)

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Future directions:

- ▶ Can training GEBMs be improved?
 - ▶ Better than a two-step training (one step?)
 - ▶ Is latent space MCMC beneficial during training⁷?
- ▶ Generalization of GEBMs
 - ▶ Do the modes defined by the energy match training samples? Is it bad⁸?

⁷Wu et al., “LOGAN: Latent Optimisation for Generative Adversarial Networks”.

⁸Belkin, Rakhlin, and Tsybakov, “Does data interpolation contradict statistical optimality?”

Thank you!

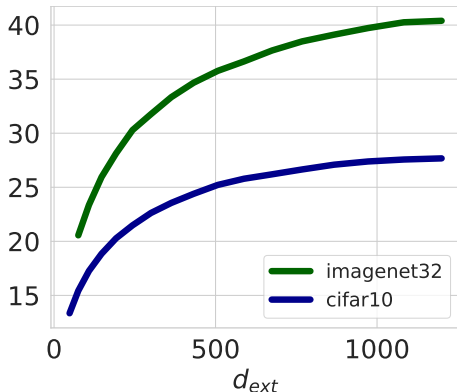
Estimating Intrinsic dimension⁹

- ▶ For a sample X , find the k -NNs X_1, \dots, X_k
- ▶ Compute distances $T_j(X) = \|X - X_j\|$
- ▶ Estimate dimension at point X :

$$d(X) = \left[\frac{1}{k-1} \sum_{j=1}^{k-1} \log \frac{T_k(X)}{T_j(X)} \right]^{-1} d_{int}$$

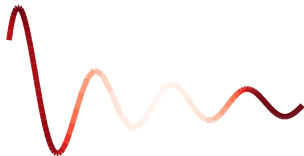
- ▶ Average over several points X and values of k .

Nearest Neighbor dimension



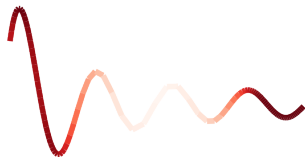
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Data with low intrinsic dimension: A toy example



Data

Data with low intrinsic dimension: A toy example



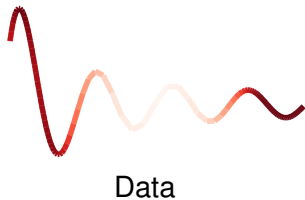
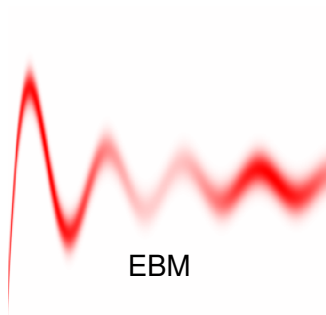
Data

$$z \sim \text{Unif}[0, 1]$$

$$\tilde{z} = \tau \downarrow (z)$$

$$X = G_{\theta^*} \downarrow (\tilde{z}), \quad X_1 = \tilde{z}$$

Data with low intrinsic dimension: A toy example

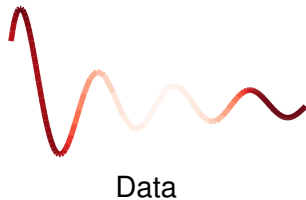
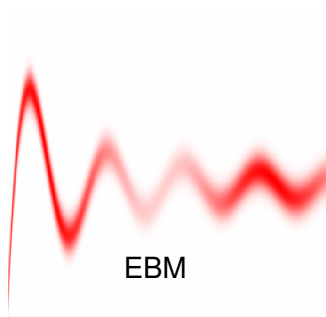


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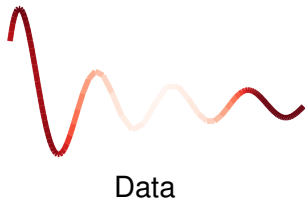
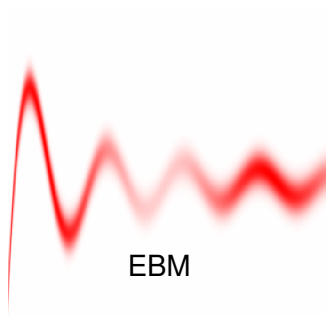
Data with low intrinsic dimension: A toy example



$$p(X) \propto \exp(-E(X))$$
$$E(X) = \frac{1}{2\sigma^2} \|G_\theta(X_1) - X\|^2 + A_\theta(X_1)$$

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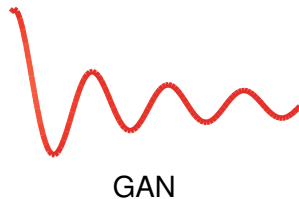
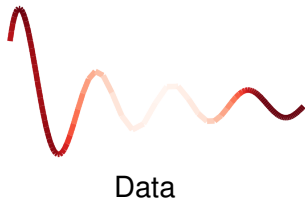
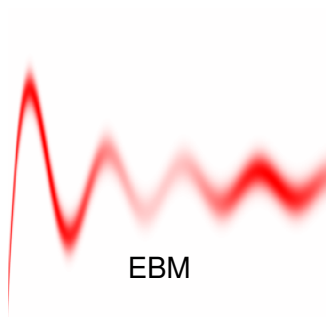


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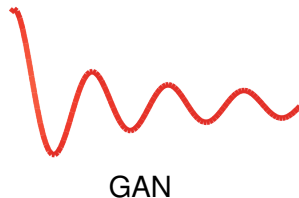
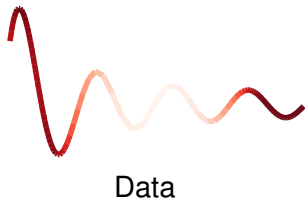
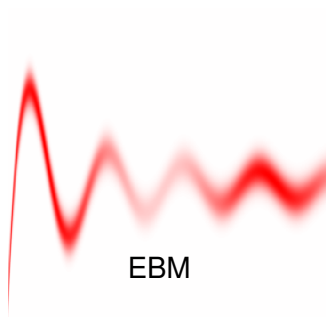


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Generator

$$z \sim \text{unif}[0, 1]$$

$$X = G_\theta^\downarrow(z)$$

Critic

$MLP(X)$



Belkin, Mikhail, Alexander Rakhlin, and Alexandre B Tsybakov. “Does data interpolation contradict statistical optimality?” In: The 22nd International Conference on Artificial Intelligence and Statistics. PMLR. 2019, pp. 1611–1619.



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