

Maximum Mean Discrepancy Gradient Flow

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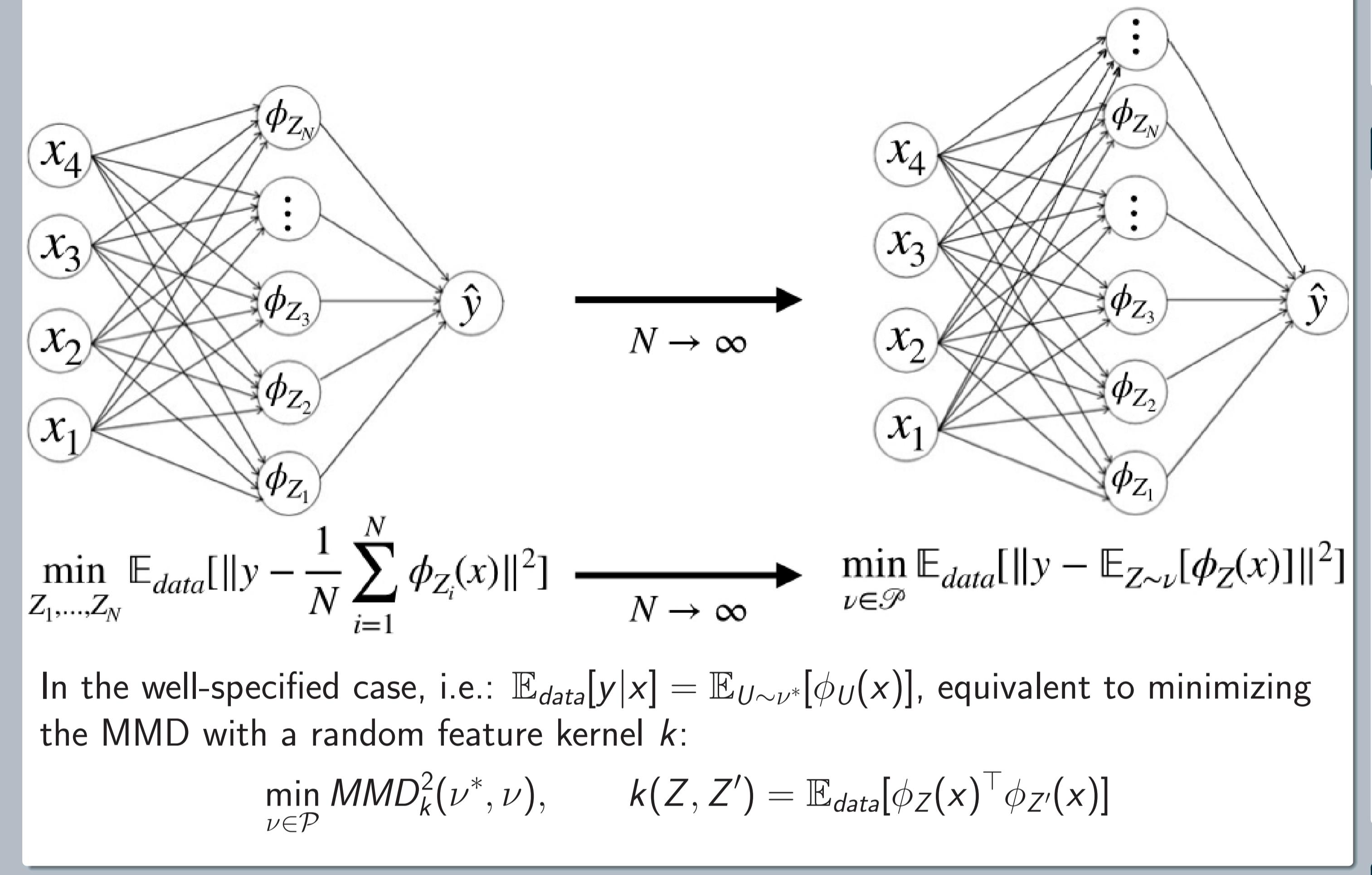
Overview

General setting:

- ✓ Non-convex optimization in probability space with the Maximum Mean Discrepancy as a cost function.
- ✓ Interested in Gradient descent dynamics in the limit of large samples $N \rightarrow \infty$.
- Goals:**
 - ✓ Criterion for global convergence of gradient descent when N approaches infinity.
 - ✓ New algorithm based on noise-injection to improve convergence.
 - ✓ Application 1: Optimization of neural networks.
 - ✓ Application 2: Criterion to characterise convergence in Implicit Generative models.

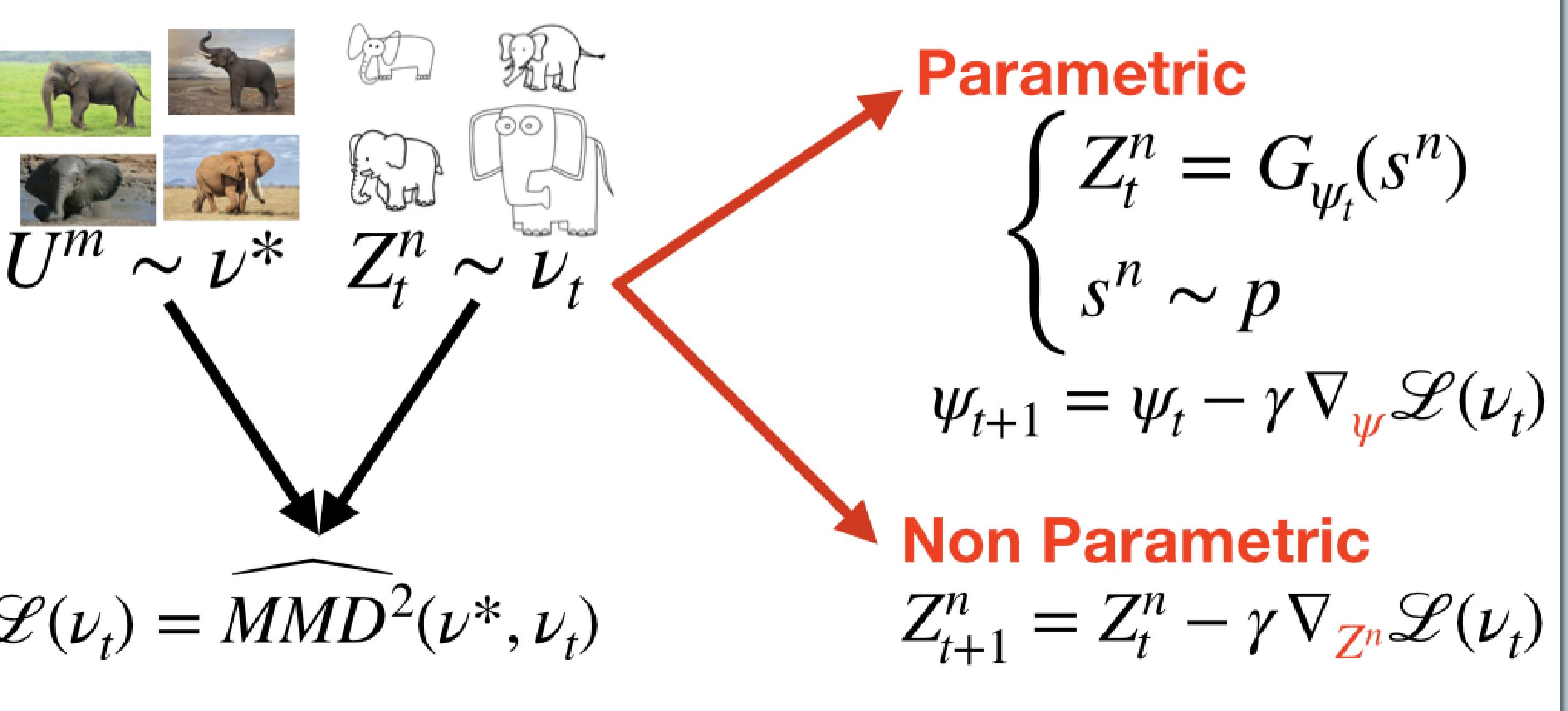
Motivation 1: Gradient Descent dynamics in neural networks

Easier to characterize the gradient descent dynamics in the Mean-field limit [3, 7]



Motivation 2: Implicit Generative models

- Good performance for Implicit generative models using the MMD as a loss [5, 2, 1].
- Hard to characterize global convergence.



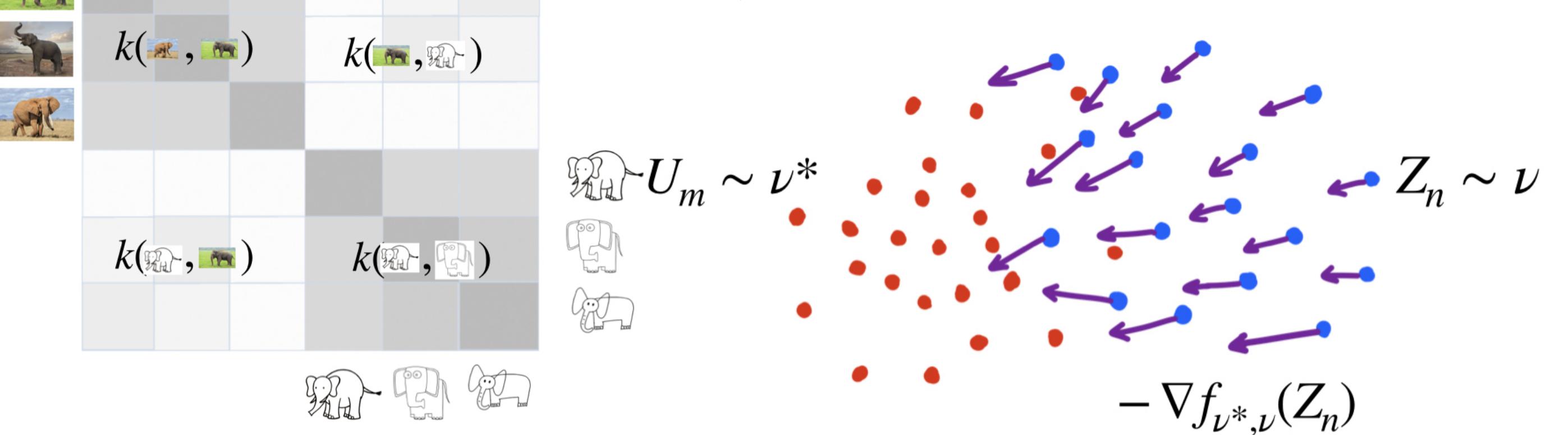
Maximum Mean Discrepancy (MMD)

The MMD is a distance between probability distributions defined using a positive semi-definite kernel k [4]:

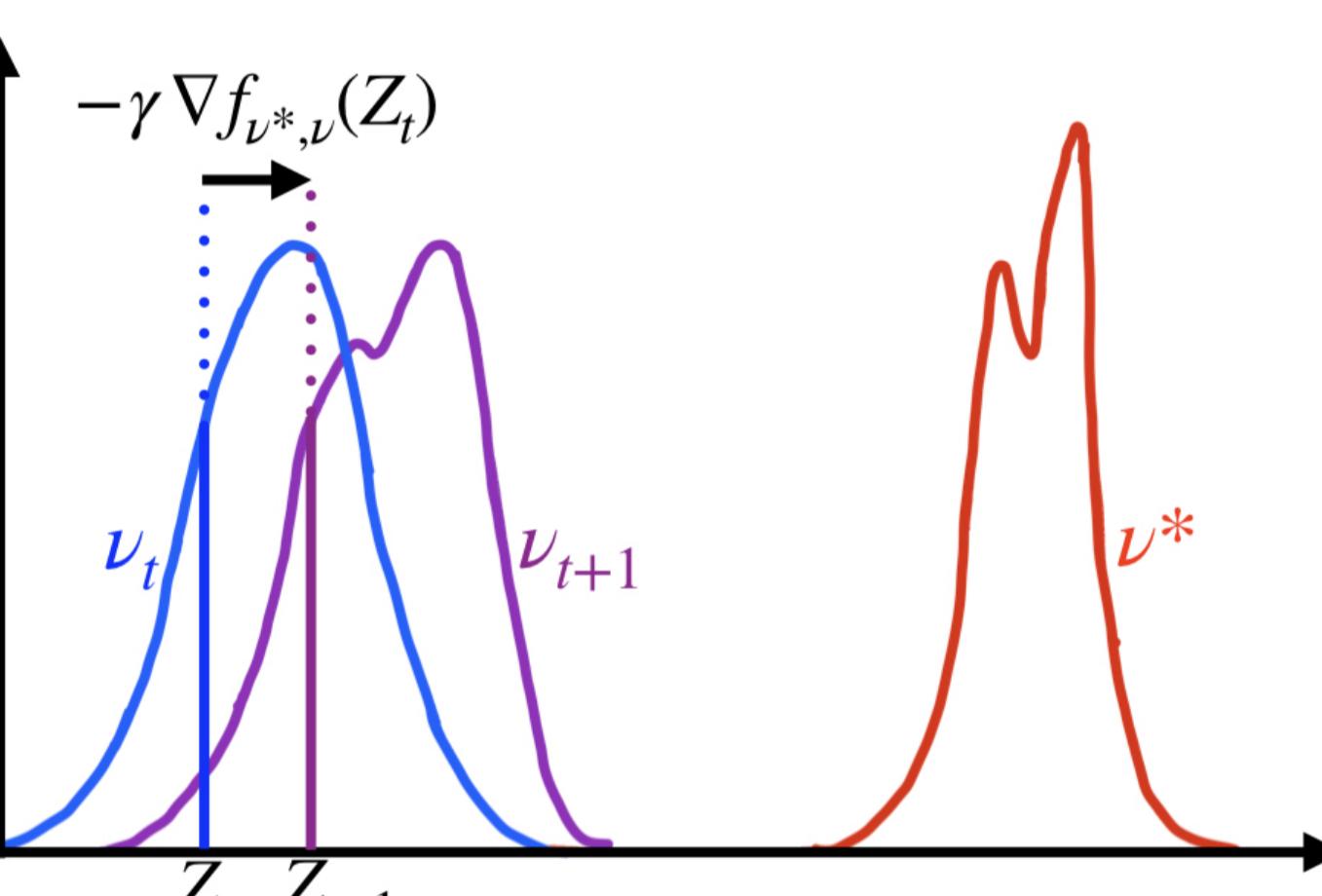
$$\frac{1}{2} MMD_k^2(\nu^*, \nu) = \frac{1}{2} \mathbb{E}_{Z, Z' \sim \nu} [k(Z, Z')] - \mathbb{E}_{Z \sim \nu} [k(Z, U)] + \frac{1}{2} \mathbb{E}_{U, U' \sim \nu} [k(U, U')]$$

- ✓ Easy to estimate from samples: ✓ Can be interpreted as the energy relative to a potential function $f_{\nu^*, \nu} := \frac{\delta}{\delta \nu} MMD_k^2(\nu^*, \nu)$

$$f_{\nu^*, \nu}(z) = \mathbb{E}_{Z \sim \nu} [k(Z, z)] - \mathbb{E}_{U \sim \nu} [k(U, z)]$$



Gradient Flow of the MMD



- Equivalent to Gradient descent when ν_t restricted to the form: $= \frac{1}{N} \sum_{n=1}^N \delta_{Z_t^n}$.
- Stationarity distribution ν_∞ satisfies: $\mathbb{E}_{Z \sim \nu_\infty} [\|\nabla f_{\nu^*, \nu_\infty}(Z)\|^2] = 0$

Discrete time: $Z_{t+1} = Z_t - \gamma \nabla f_{\nu^*, \nu_t}(Z_t), \quad Z_t \sim \nu_t$

Continuous time: $dZ_t = -\nabla f_{\nu^*, \nu_t}(Z_t), \quad Z_t \sim \nu_t$

Mc-Kean Vlasov Dynamics

Continuity equation: $\partial_t \nu_t = \text{div}(\nu_t \nabla f_{\nu^*, \nu_t})$

$$-\nabla_{\nu} \frac{1}{2} MMD^2(\nu^*, \nu_t)$$

Theory: Global convergence

- Criterion for convergence of the gradient flow: *Negative Sobolev Distance*:

$$S(\nu^* | \nu_t) := \sup_{\substack{g \in \mathcal{L}_c(\nu_t) \\ \|\nabla g\|_{L_2(\nu_t)} \leq 1}} \mathbb{E}_{Z \sim \nu^*} [g(Z)] - \mathbb{E}_{Z \sim \nu_t} [g(Z)]$$

Assume that $S(\nu^* | \nu_t) \leq C$ for all t , and that k is a characteristic kernel, then ν_t converges weakly towards ν^* . Moreover:

$$MMD^2(\nu^*, \nu_t)^2 \leq \frac{1}{MMD^2(\nu^*, \nu_0) + 4\gamma C^{-1} t}$$

- Criterion for convergence of the noise injection algorithm:

• Decreasing direction:

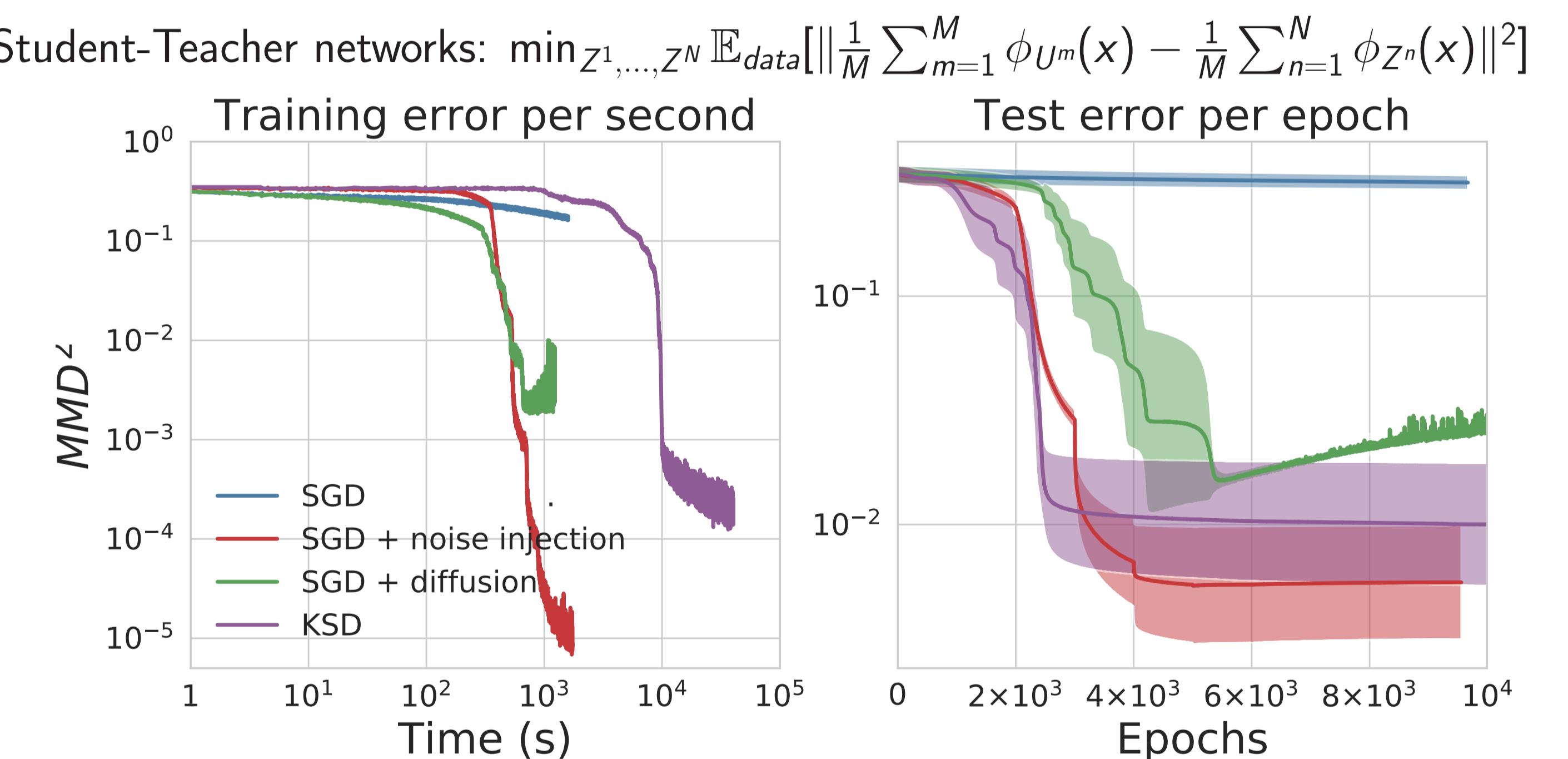
$$4\gamma^2 \beta^2 MMD^2(\nu^*, \nu_t) \leq \mathbb{E}_{\substack{Z \sim \nu_t \\ W \sim \mathcal{N}(0,1)}} [\|\nabla f_{\nu^*, \nu_t}(Z + \beta_t W)\|^2]$$

• Large noise: $\sum_{i=0}^t \beta_i^2 \rightarrow \infty$

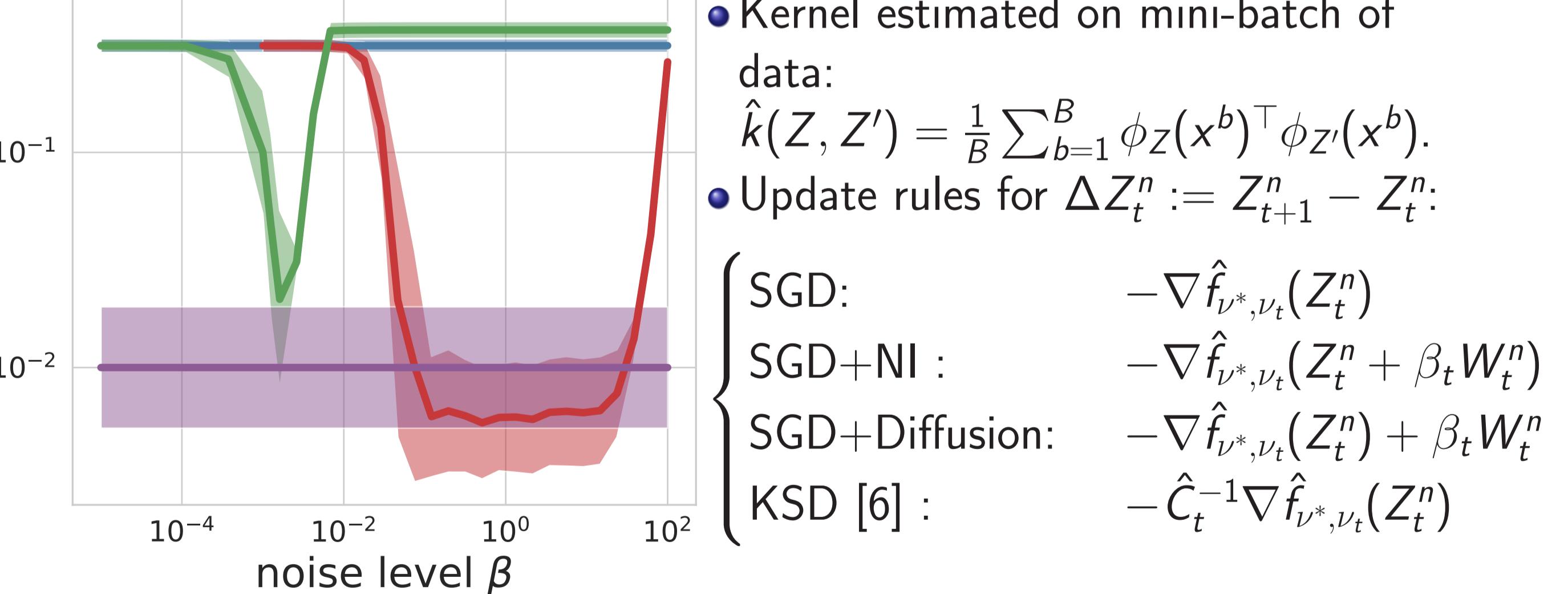
Then for some constant L :

$$MMD^2(\nu^*, \nu_t) \leq MMD(\nu^*, \nu_0) e^{-4\gamma^2(1-3\gamma L) \sum_{i=0}^t \beta_i^2}$$

Experimental Comparison



Sensitivity to noise (Test error)



Bibliography

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